

<p>First Flight Student</p>	<p>Inspect Drone/Setup</p> <p>Look at props,</p> <p>Looking for nicks, warps, attachment etc.</p> <p>Look at Battery, is it charged. With good non-blinking lights. Swelling, warm, etc.</p> <p>Look at Drone, Inspect for landing gear.</p> <p>Fill out preflight check list provided by RPIC</p>	<p>1st Flight: 1 auto Launch/Land:</p> <p>Auto Start Drone/</p> <p>Auto Land</p> <p>using no sticks, just start/land button</p> <p>Switch drone to Tripod mode</p>	<p>1st Flight :2 Manual Start/ lift drone to 15 ft Yaw left stick 360 both directions slowly, using pitch right stick, forward slowly over landing area using, pitch go backwards/ back to landing/ Roll side to side over landing target Realign drone over landing target,</p> <p>land using right stick over landing pad.</p> <p>Do all 3 students.</p>	<p>2nd Flight:</p> <p>Manual Start, lift drone to 15 ft/</p> <p>move drone with pitch/right stick to outer limit of square,</p> <p>Create a Square: use yaw, (left stick)/to the right to line up with upper right cone, use pitch (right stick)/ forward to slowly fly to right cone. Stop</p> <p>use yaw/left stick to ¼ turn to face bottom right cone. Repeat. Counter clockwise direction, Do the square both clockwise and counter clockwise</p> <p>Alight over LZ land. All 3 students</p>	<p>3rd Flight if time allows... (will cont. next flight)</p> <p>Manual Start, Lift drone to 15ft slowly/ start at the center of the back row, again using yaw/left stick to right to align with right top cone and use right stick/pitch to slowly move towards cone, while slowly introducing left stick/yaw to right. Turning the drone inside the cones from point to point until you create a circle inside the cones. Land.</p>
Beth					
Brenda					
Bob					